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1: Local Curve Theory

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An online book on differential geometry which I like better than the Do Carmo textbook. In this book there is a careful statement of the Inverse and Implicit Function Theorems on page 3 and a proof that the three definitions of a regular surface are equivalent on page 6.

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Problem numbers refer to the do Carmo text. 1.

1.2-1 The curve $\gamma(s) = (\cos(s), \sin(s))$ parameterizes the circle $x^2 + y^2 = 1$ in the clockwise orientation.

2.

1.2-2 The distance from the point $\gamma(t) \in \mathbb{R}^n$ to the

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originis $f(t) = |r(t)|$. At a point where this distance assumes its minimum, the derivative of the function must vanish.

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One of the most widely
used texts in its field,
this volume introduces
the differential
geometry of curves and
surfaces in both local

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and global aspects. The presentation departs from the traditional approach with its more extensive use of elementary linear algebra and its emphasis on basic geometrical facts rather than machinery or random details. Many examples and exercises enhance the clear, well-written exposition, along with

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hints and answers to some of the problems. The treatment begins with a chapter on curves, followed by explorations of regular surfaces, the geometry of the Gauss map, the intrinsic geometry of surfaces, and global differential geometry. Suitable for advanced undergraduates and graduate students of

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mathematics, this text's prerequisites include an undergraduate course in linear algebra and some familiarity with the calculus of several variables. For this second edition, the author has corrected, revised, and updated the entire volume.

An application of
differential forms for the

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study of some local and global aspects of the differential geometry of surfaces. Differential forms are introduced in a simple way that will make them attractive to "users" of mathematics. A brief and elementary introduction to differentiable manifolds is given so that the main theorem, namely Stokes' theorem, can be

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Geometry is presented in its natural setting. The applications consist in developing the method of moving frames expounded by E. Cartan to study the local differential geometry of immersed surfaces in \mathbb{R}^3 as well as the intrinsic geometry of surfaces. This is then collated in the last chapter to present Chern's proof of the Gauss-Bonnet

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surfaces.

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Elementary, yet authoritative and scholarly, this book offers an excellent brief introduction to the classical theory of differential geometry. It is aimed at advanced undergraduate and graduate students who will find it not only

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highly readable but replete with illustrations carefully selected to help stimulate the student's visual understanding of geometry. The text features an abundance of problems, most of which are simple enough for class use, and often convey an interesting geometrical fact. A selection of more

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difficult problems has been included to challenge the ambitious student. Written by a noted mathematician and historian of mathematics, this volume presents the fundamental conceptions of the theory of curves and surfaces and applies them to a number of examples. Dr. Struik has

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enhanced the treatment with copious historical, biographical, and bibliographical references that place the theory in context and encourage the student to consult original sources and discover additional important ideas there. For this second edition, Professor Struik made some corrections and added an appendix with

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a sketch of the application of Cartan's method of Pfaffians to curve and surface theory. The result was to further increase the merit of this stimulating, thought-provoking text — ideal for classroom use, but also perfectly suited for self-study. In this attractive, inexpensive paperback edition, it belongs in the

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library of any
mathematician or
student of mathematics
interested in differential
geometry.

This book is a
posthumous publication
of a classic by Prof.
Shoshichi Kobayashi,
who taught at U.C.
Berkeley for 50 years,
recently translated by
Eriko Shinozaki

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Nagumo and Makiko

Sumi Tanaka. There are five chapters: 1. Plane

Curves and Space

Curves; 2. Local Theory of Surfaces in Space; 3.

Geometry of Surfaces;

4. Gauss–Bonnet

Theorem; and 5.

Minimal Surfaces.

Chapter 1 discusses

local and global

properties of planar

curves and curves in

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space. Chapter 2 deals with local properties of surfaces in 3-dimensional Euclidean space. Two types of curvatures — the Gaussian curvature K and the mean curvature H — are introduced. The method of the moving frames, a standard technique in differential geometry, is introduced in the context of a

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surface in 3-dimensional Euclidean space. In Chapter 3, the Riemannian metric on a surface is introduced and properties determined only by the first fundamental form are discussed. The concept of a geodesic introduced in Chapter 2 is extensively discussed, and several examples of geodesics are presented

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with illustrations.

Chapter 4 starts with a simple and elegant proof of Stokes' theorem for a domain. Then the Gauss–Bonnet theorem, the major topic of this book, is discussed at great length. The theorem is a most beautiful and deep result in differential geometry. It yields a relation between the integral of

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the Gaussian curvature over a given oriented closed surface S and the topology of S in terms of its Euler number $\chi(S)$. Here again, many illustrations are provided to facilitate the reader's understanding. Chapter 5, Minimal Surfaces, requires some elementary knowledge of complex analysis. However, the author

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retained the introductory nature of this book and focused on detailed explanations of the examples of minimal surfaces given in Chapter 2.

An introductory textbook on the differential geometry of curves and surfaces in 3-dimensional Euclidean space,

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Geometry in its simplest,
most essential form.

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solutions. Includes 99
illustrations.

This introductory
textbook puts forth a
clear and focused point
of view on the
differential geometry of
curves and surfaces.

Following the modern
point of view on

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differential geometry, the book emphasizes the global aspects of the subject. The excellent collection of examples and exercises (with hints) will help students in learning the material.

Advanced undergraduates and graduate students will find this a nice entry point to differential geometry. In order to

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study the global properties of curves and surfaces, it is necessary to have more sophisticated tools than are usually found in textbooks on the topic. In particular, students must have a firm grasp on certain topological theories. Indeed, this monograph treats the Gauss-Bonnet theorem and discusses the Euler

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Geometry. The authors also cover Alexandrov's theorem on embedded compact surfaces in \mathbb{R}^3 with constant mean curvature. The last chapter addresses the global geometry of curves, including periodic space curves and the four-vertices theorem for plane

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curves that are not necessarily convex.

Besides being an introduction to the lively subject of curves and surfaces, this book can also be used as an entry to a wider study of differential geometry. It is suitable as the text for a first-year graduate course or an advanced undergraduate course.

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This text presents a graduate-level introduction to differential geometry for mathematics and physics students. The exposition follows the historical development of the concepts of connection and curvature with the goal of explaining the Chern–Weil theory of characteristic classes on

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a principal bundle.

Along the way we encounter some of the high points in the history of differential geometry, for example, Gauss' Theorema Egregium and the Gauss–Bonnet theorem.

Exercises throughout the book test the reader's understanding of the material and sometimes illustrate

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extensions of the theory.

Initially, the prerequisites for the reader include a passing familiarity with manifolds. After the first chapter, it becomes necessary to understand and manipulate differential forms. A knowledge of de Rham cohomology is required for the last third of the text. Prerequisite

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Geometry is contained in

author's text An

Introduction to

Manifolds, and can be
learned in one semester.

For the benefit of the
reader and to establish
common notations,

Appendix A recalls the
basics of manifold
theory. Additionally, in
an attempt to make the
exposition more self-
contained, sections on

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algebraic constructions such as the tensor product and the exterior power are included.

Differential geometry, as its name implies, is the study of geometry using differential calculus. It dates back to Newton and Leibniz in the seventeenth century, but it was not until the nineteenth century, with the work of Gauss on

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surfaces and Riemann

on the curvature tensor,
that differential

geometry flourished and

its modern foundation

was laid. Over the past

one hundred years,

differential geometry

has proven

indispensable to an

understanding of the

physical world, in

Einstein's general theory

of relativity, in the

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theory of gravitation, in gauge theory, and now in string theory.

Differential geometry is also useful in topology, several complex variables, algebraic geometry, complex manifolds, and dynamical systems, among other fields. The field has even found applications to group theory as in Gromov's

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work and to probability theory as in Diaconis's work. It is not too far-fetched to argue that differential geometry should be in every mathematician's arsenal.

Central topics covered include curves, surfaces, geodesics, intrinsic geometry, and the Alexandrov global angle comparison theorem

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Many nontrivial and original problems (some with hints and solutions)

Standard theoretical material is combined with more difficult theorems and complex problems, while maintaining a clear distinction between the two levels

Elementary Differential
Geometry presents the

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main results in the differential geometry of curves and surfaces

suitable for a first course on the subject.

Prerequisites are kept to an absolute minimum – nothing beyond first courses in linear algebra and multivariable calculus – and the most direct and straightforward approach is used

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throughout. New features of this revised and expanded second edition include: a chapter on non-Euclidean geometry, a subject that is of great importance in the history of mathematics and crucial in many modern developments. The main results can be reached easily and quickly by making use

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of the results and techniques developed earlier in the book.

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